



ATLAS/ICESat-2 L3B Annual Land Ice Height, Version 3

USER GUIDE

How to Cite These Data

As a condition of using these data, you must include a citation:

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National Snow and Ice Data Center

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This user guide cites sections in the Algorithm Theoretical Basis Document (ATBD) for Land-Ice Along-Track Products Part 2: Land-ice H(t) (ATBD for ATL11 | V03 DOI: 10.5067/P5CESGCT4MP9). To download this and other relevant documents, see the list of “Technical References” on the Data Set landing page for ATL11, Version 3:

<https://nsidc.org/data/ATL11/versions/3>

1 DATA DESCRIPTION

1.1 Parameters

This data set (ATL11, V03) contains spatially organized time series of land-ice surface heights, derived from the ATLAS/ICESat-2 L3A Land Ice Height product (ATL06, V04). Height changes are computed for repeat observations (91 days apart) along individual ICESat-2 ground tracks in polar regions.

ATL11 is intended primarily as an input for higher-level gridded products, but can also be used on its own.

1.2 File Information

1.2.1 Format

Data are provided as HDF5 formatted files. HDF is a data model, library, and file format designed specifically for storing and managing data. For more information about HDF, visit the [HDF Support Portal](#).

The HDF Group provides tools for working with HDF5 formatted data. HDFView is free software that allows users to view and edit HDF formatted data files. In addition, the HDF - EOS | Tools and Information Center web page contains [code examples](#) in Python (pyhdf/h5py), NCL, MATLAB, and IDL for accessing and visualizing ICESat-2 files.

1.2.2 File Contents

The ICESat-2 satellite acquires data along 1,387 separate RGTs, completing a “cycle” of all RGTs every 91 days. To keep file sizes manageable, some products (including ATL11) break up RGT data by region (see Figure 1 and Table 1). The ATLAS instrument is configured to make repeat measurements along RGTs in polar regions (poleward of 60° N and 60° S). This strategy allows ATL11 to construct time series of ice height changes from cycle to cycle (i.e. 91 days apart) for regions 3, 4 and 5 and 10, 11, and 12.

Each ATL11 data file contains estimated land ice heights, plus other data, for one region of one RGT. Data are stored as (r,c) arrays, where r is the number of locations with data and c is the number of cycles (i.e. repeat measurements at each M, conditions permitting). Version 3 of ATL11 contains data from Cycle 3 through Cycle 9, or seven cycles. The product will be updated annually with new data from each year's cycles.

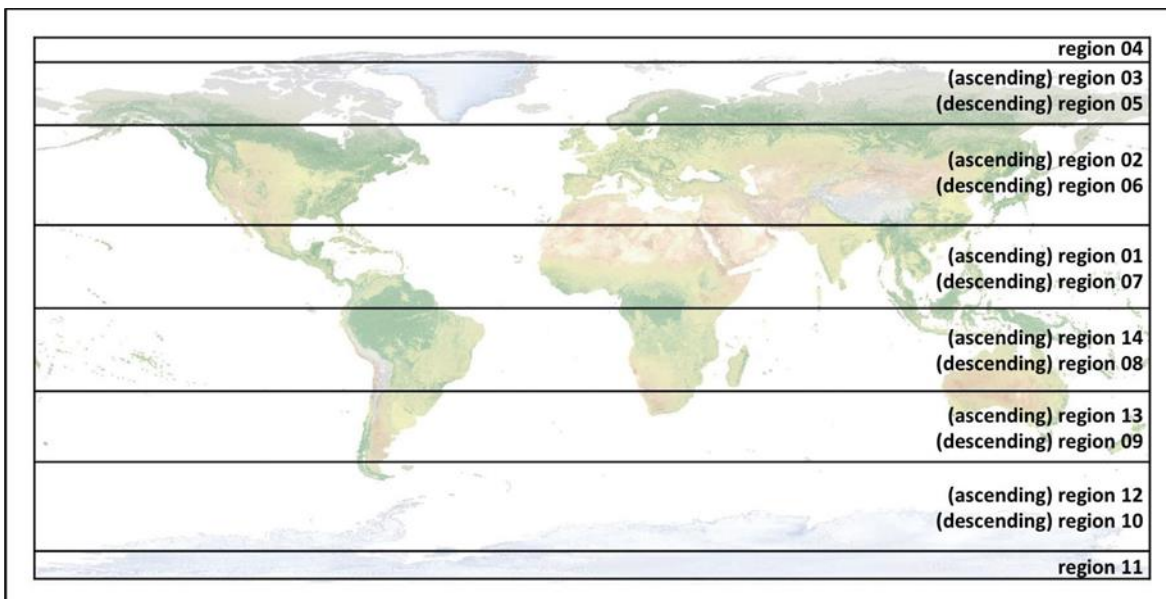


Figure 1. ATLAS/ICESat-2 region boundaries.

Table 1. ATLAS/ICESat-2 Region Latitude Bounds (A = Ascending, D = Descending)

Reg.	Latitude Bounds	Reg.	Latitude Bounds
01	Equator → 27° N (A)	08	Equator → 27° S (D)
02	27° N → 59.5° N (A)	09	27° S → 50° S (D)
03	59.5° N → 80° N (A)	10	50° S → 79° S (D)
04	80° N (A) → 80° N (D)	11	79° S (D) → 79° S (A)
05	80° N → 59.5° N (D)	12	79° S → 50° S (A)
06	59.5° N → 27° N (D)	13	50° S → 27° S (A)
07	27° N (D) → Equator	14	27° S → Equator (A)

1.2.3 Naming Convention

Data files are named according to the following convention:

ATL11_050611_0309_003_01.h5

ATL11_[tttt][ss]_[cccc]_[vvv_rr].h5

The following table describes the file naming convention variables:

Table 2. File Naming Convention Variables and Descriptions

Variable	Description
ATL11	ATLAS/ICESat-2 L3B Annual Land Ice Height product
tttt	Reference Ground Track (RGT). The ICESat-2 mission has 1,387 RGTs, numbered from 0001 to 1387.
ss	Region (orbital segment) number. Region numbers for the ICESat-2 mission range from 01-14, however, data files for this product are only produced for regions that lie poleward of 60° N and 60° S. This corresponds to regions 3, 4, 5, 10, 11, and 12.
cccc	First and last cycles of data included in the file. E.g., “0309” would indicate the file contains data from cycles 3–9, inclusive.
vvv_rr	Version and revision number (see Note)

Note: From time to time, NSIDC receives duplicate, reprocessed granules from our data provider. These granules have the same file name as the original granule (i.e. date, time, ground track, cycle, and segment number), but the revision number has been incremented. Although NSIDC deletes the superseded granule, the process can take several days. As such, if you encounter multiple granules with the same file name but different revision numbers, please use the granule with the highest revision number.

1.2.4 Data Groups

Within data granules, similar variables such as science data, instrument parameters, and metadata are grouped together according to the HDF model. ATL11 data are organized within the following top-level groups:

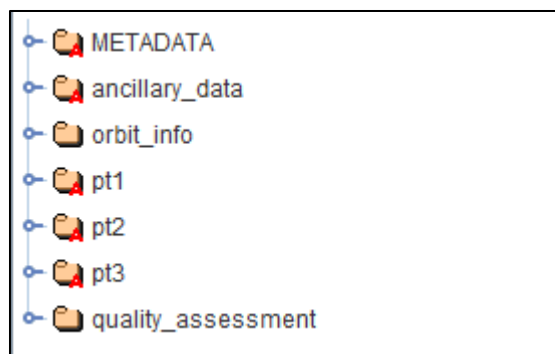


Figure 2. ATL11 data groups shown in HDFView.

The following sections summarize the contents of the above data groups and identify some parameters of interest. For a list and description of all output parameters on the ATL11 product, see “Section 4.0 | Land Ice Products: Land Ice H(T)” in the ATBD for ATL11.

1.2.4.1 METADATA

- ISO19115 structured metadata with sufficient content to generate the required geospatial metadata

1.2.4.2 ancillary_data

- Parameters that pertain to the granule in its entirety, such as product and instrument characteristics and/or processing constants

1.2.4.3 orbit_info

- Parameters that are constant for a granule such as the RGT number and cycle, the spacecraft orientation, and parameters passed through to higher-level products

1.2.4.4 pt[x]

These three data groups, one for each pair track, contain the primary science parameters for this data set, stored at the top level and in subgroups. Parameters at the top level include:

- Mean corrected height (`h_corr`) and corrected height error (`h_corr_sigma`)
- Latitude (`latitude`) and longitude (`longitude`) for each ATL11 data point
- QA flag (`quality_summary`)

The `pt[x]/cycle_stats/` subgroup contains summary information about segments for each reference point, including the uncorrected mean heights for reference surfaces, blowing snow and cloud indicators, and geolocation and height misfit statistics.

The pt[x] /ref_surf/ subgroup contains parameters that describe the reference surface fit at each reference point, including slope information from ATL06, the polynomial coefficients used for the fit, and misfit statistics.

The pt[x] /crossing_track_data/ subgroup contains the corrected heights, latitude/longitude locations, and associated data at crossover locations (i.e. where ICESat-2 pair tracks cross). See “Section 2.3.3 | Crossing-Track Data” of this user guide for more information.

1.2.4.5 quality_assessment

- Quality assessment flags that indicate whether or not the granule passed automatic QA (qa_granule_pass_fail) and why (qa_granule_fail_reason).

1.2.5 Browse Files

Each ATL11 data file has a corresponding HDF5 browse file which contains eight figures. The browse file follows the same naming convention as their corresponding data file, but with _BRW appended. For example:

- ATL11_015611_0309_001_01.h5
- ATL11_015611_0309_001_01_BRW.h5.

Two of these figures are located in the default group (default1, default2). Figure default1 depicts in three panels height data, numbers of cycles with valid height data and the change in height over time. The background of all three panels is the gradient DEM in gray scale. Figure default2 shows a histogram of the number of valid height measurement for each beam pair and cycle. For more information about browse files, see the ATBD for ATL11 | Section 7.0. Browse Products.

Spatial Information

1.2.6 Coverage

Coverage spans the regions poleward of 60° N and 60° S. However, data files are only generated for regions in which the satellite makes repeat-track measurements (see note) and crosses a land surface (i.e. does not lie entirely over open ocean). This corresponds to regions 3, 4, 5 and 10, 11, and 12 (See Figure 1 and Table 1).

The ICESat-2 orbit does not cross directly over the North and South poles. This produces a gap in coverage, or “pole hole,” between 88° and 90° in both the Northern and Southern Hemisphere.

1.2.7 Resolution

ATL11 data are posted every 60 m, at locations that correspond to the center of every third ATL06 segment (ATL06 segment ID). The ATL11 algorithm uses all available ATL06 segments whose centers lie within 60 m of the central segment, such that ATL11 data are derived from measurements spanning 120 m in the along-track direction.

1.2.8 Geolocation

The following table provides information for geolocating this data set.

Table 3. Geolocation Details

Geographic coordinate system	WGS 84
Projected coordinate system	WGS 84
Longitude of true origin	Prime Meridian, Greenwich
Latitude of true origin	N/A
Scale factor at longitude of true origin	N/A
Datum	World Geodetic System 1984
Ellipsoid/spheroid	WGS 84
Units	degree
EPSG code	4326
PROJ4 string	+proj=longlat +datum=WGS84 +no_defs
Reference	https://epsg.io/4326

1.3 Temporal Information

1.3.1 Coverage

Data span 29 March 2019 (beginning of cycle 3) to 24 December 2020 (end of cycle 8). Note, however, that data are only available at times when the satellite is poleward of 60° N and 60° S (regions 3, 4, 5 and 10, 11, and 12) and crossing land. Subsequent versions of this data set will be released approximately annually. Each new version will add the data acquired since the previous version (four cycles per year).

1.3.2 Resolution

Temporal resolution is 91 days.

The ICESat-2 satellite traverses each of its 1,387 RGTs once every 91 days—i.e., the satellite has a 91-day repeat cycle. The ATLAS instrument is configured to make repeat measurements along RGTs in polar regions (poleward of 60° N and 60° S).

2 DATA ACQUISITION AND PROCESSING

The following sections summarize how ATL11 data are processed. Users seeking additional details should consult the referenced sections in the ATBD for ATL11. To download this document, see “Technical References” on the ATL11, Version 1 Data Set landing page at <https://nsidc.org/data/ATL11/versions/3>.

2.1 Background

A number of successful techniques have been used to determine elevation changes from repeat-track data from ICESat/GLAS, the predecessor to ATLAS/ICESat-2. For example, where surface slopes are small relative to background geophysical processes, height changes have been isolated by subtracting the mean height from a collection of measurements along the same repeat track. In regions where off-track surface slopes are not negligible, height changes have been recovered by subtracting the mean height plus an estimate of the surface slope.

ATL11 extends this approach by fitting low-degree polynomial surfaces to ATL06 surface heights and surface-slope information and using these small (< 1 km) patches to correct for sub-kilometer surface topography.

2.2 Acquisition

ATL11 is generated from ATL06 repeat track data. As described above in “Section 1.2.2 | File Information,” the ATL06 product is distributed as granules (files) that span about 1/14th of an orbit. ATL11 data are processed from ATL06 granules in regions 3, 4 and 5 and 10, 11, and 12.

2.3 Processing

2.3.1 Coordinate System

Although ATL11 heights are geolocated with lat/lon coordinates, computations are performed using the ATL06 along-track coordinate system. Briefly, this coordinate system is defined separately for

each RGT, with an x-coordinate that starts (and ends) at the equator and increases in the ascending direction (north from the equator). The y-coordinate is perpendicular to the x-coordinate and positive to the left. Thus, the x-coordinate for each RGT runs from zero to about 4×10^7 m and the y-coordinate runs from about -3.3×10^3 m (the right beam pair) to approximately 3.3×10^3 m (the left beam pair).

2.3.2 Along-Track Ice Heights

ATL11 output data are centered on reference points which share the same along-track coordinate as the central ATL06 segment, but are displaced in the across-track direction to better match the aggregate location of the ATL06 measurements from all of the cycles present.

ATL06 land ice height estimates consist of 40 m overlapping surface segments whose centers are spaced 20 m apart along each of ICESat-2's three reference pair tracks (RPTs). These segments are displaced horizontally both relative to the RPT and to one another due to small imprecisions in measurement locations on the ground (a few tens of meters or less). ATL11 heights are corrected for these offsets between the reference tracks and the location of the ATLAS measurements by using ATL06 height and local surface slope information to construct a reference surface.

For a set of reference points spaced every 60 meters along each RPT (centered on every third segment center), the ATL11 algorithm considers all ATL06 segments whose centers lie within 60 m along-track and 65 m across-track of a reference point. As such, the fit for each ATL11 segment contains as many as seven distinct along-track ATL06 segments from each beam and cycle.

To calculate the reference surface using the most reliable subset of available data, the algorithm performs tests on these segments and selects a subset with self-consistent slopes and small errors, which it uses to define a time-variable surface height and a polynomial surface-shape model. The algorithm then applies the surface-shape model to calculate corrected heights for segments which were not chosen for the initial subset.

Figure 3 shows the data selection process as a flow chart. The ATBD for ATL11 describes these steps in "Section 3.0 | Algorithm Theory: Derivation of Land Ice H (T)." This section includes subsections that detail: input data editing (Section 3.1); reference surface shape computations (Section 3.2.); corrected height calculations for segments not included in the initial subset (Section 3.4); parameter averaging (Section 3.7); and output data editing (Section 3.8).

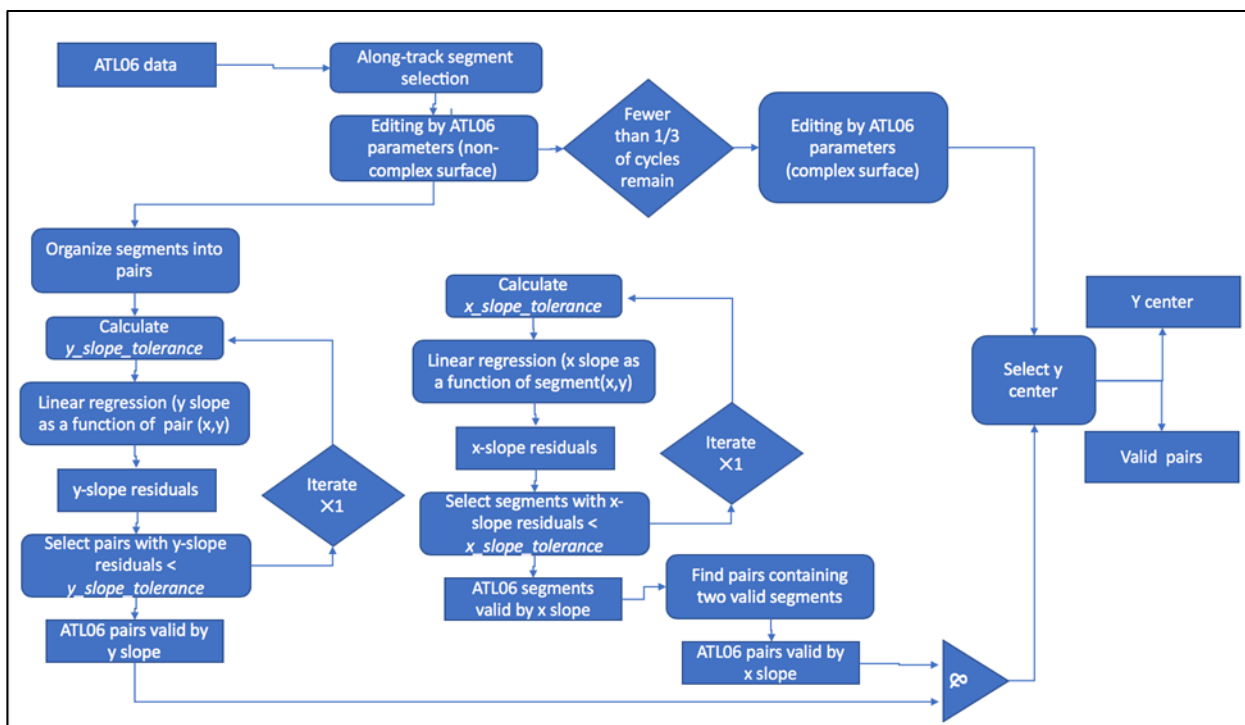


Figure 3. Flow Chart Showing the Data Selection Process (source: ATBD for ATL11)

2.3.3 Crossing-Track Data

Locations where ground tracks cross provide opportunities to check the accuracy of measurements by comparing surface-height estimates between different ground tracks. In addition, these crossing data offer additional temporal detail than the 91-day repeat cycle.

At crossover points, the algorithm corrects elevations using the reference surface computed for the along-track segments at that location. This computation is detailed in “Section 3.6 | Calculating Shape-Corrected Heights For Crossing-Track Data” in the ATBD for ATL11.

2.4 Quality, Errors, and Limitations

The ATL11 algorithm propagates errors for each step and computes formal height error estimates that account for sampling error in ATL06 and systematic errors due to geolocation errors in the slope of the surface-shape model. Formal error estimates are described in the ATBD for ATL11 in “Section 3.3 | Reference-shape Correction Error Estimates” and “Section 3.5 | Calculating Systematic Error Estimates”.

ATL11 error estimates are stored in the following locations:

- pt[x]
 - h_corr_sigma (error in the corrected height)

- h_corr_sigma_systematic (all errors correlated at scales larger than a single fit center)
- pt[x]/crossing_track_data/
 - h_corr_sigma (error in the crossing-track corrected height)
 - h_corr_sigma_systematic (all crossing-track errors correlated at scales larger than a single fit center)
- pt[x]/cycle_stats/
 - sigma_geo_at (along-track geolocation error)
 - sigma_geo_h (vertical geolocation error)
 - sigma_geo_xt (cross-track geolocation error)
- pt[x]/ref_surf/
 - misfit_RMS (surface polynomial RMS misfit)
 - misfit_chi2r (surface polynomial chi-square misfit)
 - poly_coeffs_sigma (errors in the polynomial coefficients)
 - slope_change_rate_x_sigma (x-component)
 - slope_change_rate_y_sigma (y-component)

3 VERSION HISTORY

Version 3 (April 2021)

Changes for this version include:

- Addition of new parameter pt[x]/ref_surf/geoid_h, a weighted average of the geoid_h parameter from ATL06. This allows users to compare ATL11 height estimates to an approximation of local sea level.
- Addition of root attribute short_name.
- Modifications in quality assurance to allow for partial population of beam pair groups
- Modifications in ancillary_data to correctly reflect ATL11 release and version numbers
- Corrections of /orbit_info/sc_orient_time as the dimension scale in that group
- Addition of missing root level attributes.
- Modification of long_name of /pt[x]/crossing_track_data/h_corr to read 'corrected height'.
- Bug fix that prevented the dynamic atmosphere correction from being calculated for along-track data.

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5 DOCUMENT INFORMATION

5.1 Publication Date

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5.2 Date Last Updated

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APPENDIX A: ATLAS/ICESAT-2 DESCRIPTION

The ATLAS instrument and ICESat-2 observatory utilize a photon-counting lidar and ancillary systems (GPS and star cameras) to measure the time a photon takes to travel from ATLAS to Earth and back again and to determine the photon's geodetic latitude and longitude. Laser pulses from ATLAS illuminate three left/right pairs of spots on the surface that as ICESat-2 orbits Earth trace out six ground tracks that are typically about 14 m wide. Each ground track is numbered according to the laser spot number that generates it, with ground track 1L (GT1L) on the far left and ground track 3R (GT3R) on the far right. Left/right spots within each pair are approximately 90 m apart in the across-track direction and 2.5 km in the along-track direction. The ATL06 data product is organized by ground track, with ground tracks 1L and 1R forming pair one, ground tracks 2L and 2R forming pair two, and ground tracks 3L and 3R forming pair three. Each pair also has a Pair Track—an imaginary line halfway between the actual location of the left and right beams (see Figures A1 and A2). Pair tracks are approximately 3 km apart in the across-track direction.

The beams within each pair have different transmit energies—so-called weak and strong beams—with an energy ratio between them of approximately 1:4. The mapping between the strong and weak beams of ATLAS, and their relative position on the ground, depends on the orientation (yaw) of the ICESat-2 observatory, which is changed approximately twice per year to maximize solar illumination of the solar panels. The forward orientation corresponds to ATLAS traveling along the +x coordinate in the ATLAS instrument reference frame (see Figure A1). In this orientation, the weak beams lead the strong beams and a weak beam is on the left edge of the beam pattern. In the backward orientation, ATLAS travels along the -x coordinate, in the instrument reference frame, with the strong beams leading the weak beams and a strong beam on the left edge of the beam pattern (see Figure A2). The first yaw flip was performed on December 28, 2018, placing the spacecraft into the backward orientation. The current spacecraft orientation, as well as a history of previous yaw flips, is available in the “ICESat-2 Major Activities” tracking document (.xlsx) downloadable from the list of “Technical References” on the Data Set landing page for [ATL11, Version 3](#).

The Reference Ground Track (RGT) refers to the imaginary track on Earth at which a specified unit vector within the observatory is pointed. Onboard software aims the laser beams so that the RGT is always between ground tracks 2L and 2R (i.e. coincident with Pair Track 2). The ICESat-2 mission acquires data along 1,387 different RGTs. Each RGT is targeted in the polar regions once every 91 days (i.e. the satellite has a 91-day repeat cycle) to allow elevation changes to be detected. Cycle numbers track the number of 91-day periods that have elapsed since the ICESat-2 observatory entered the science orbit. RGTs are uniquely identified by appending the two-digit cycle number to the RGT number, e.g. 000103 (RGT 0001, cycle 03) or 138705 (RGT 1387, cycle 05).

Users should note that between 14 October 2018 and 30 March 2019 the spacecraft pointing control was not yet optimized. As such, ICESat-2 data acquired during that time do not lie along the nominal RGTs, but are offset at some distance from the RGTs. Although not along the RGT, the geolocation information for these data is not degraded.

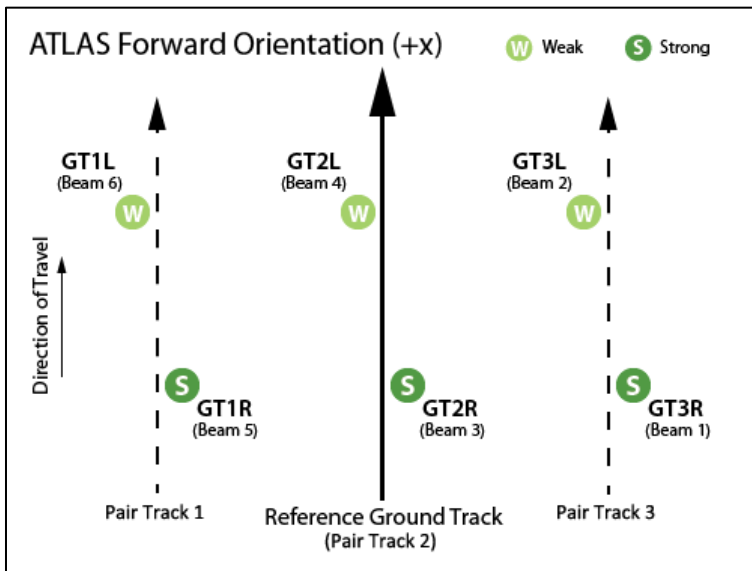


Figure A1. Spot and ground track (GT) naming convention with ATLAS oriented in the forward (instrument coordinate +x) direction.

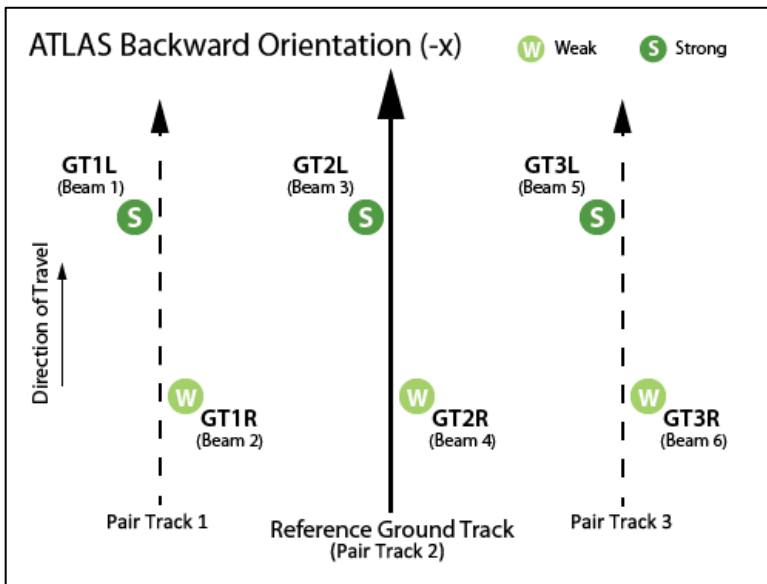


Figure A2. Spot and ground track (GT) naming convention with ATLAS oriented in the backward (instrument coordinate -x) direction.